

**3 CPD POINTS  
APPROVED**



**MAHSA  
UNIVERSITY**

# KINEMATICS OF ROBOTICS (KOR)

27<sup>th</sup> February 2020  
Thursday  
1.00pm - 5.00pm  
Auditorium, Level 9,  
Empathy Building  
MAHSA University

## WHO SHOULD ATTEND

Bachelor, Masters and PhD students, robotics engineer, robotics and automation lecturers, pupils, teachers and other professional

This talk with the aims to share, discuss and outspread knowledge of the most recent theories, issues and practices among academicians and practitioners in robotics area that relates to NAO humanoid robot walking kinematics. Our mission is to support and encourage the speaker to share his knowledge and his publication of his research work in humanoid robot walking which ultimately will contribute to the development in science and technology.

## FEES

<b>MAHSA's STUDENTS</b>	<b>RM50</b>
<b>MAHSA's STAFF</b>	<b>RM100</b>
<b>STUDENTS</b>	<b>RM80</b>
<b>OTHERS</b>	<b>RM150</b>

## SPEAKER



**PROF. DR HANAFIAH  
BIN YUSSOF**

Director of Institute Of  
Mechanical Engineering &  
Technology Advancement  
(i-META)  
Faculty of Mechanical  
Engineering, UiTM

Prof. Dr. Hanafiah Yussof is Professor at the Faculty of Mechanical Engineering, University Teknologi MARA (UiTM). He received the B. Eng Degree in Mechanical Engineering from Iwate University, Japan in 1998, M. Eng. Degree in Mechanical System Engineering from Yamagata University, Japan in 2005, and PhD Degree in Information Science from Nagoya University Japan in 2008. His research interests include humanoid robotics, medical and rehabilitation robotics, grasping and manipulation of robotic hands, tactile sensor, bio-sensor, sensor fusion, military robotics and intelligent control of mobile manipulators. Prof Dr. Hanafiah has published more than 100 publications in international journals, books, book chapters, conference proceedings, newspaper and magazines. He is the editor of book "Robot Localization and Map Building", published by In-Tech Press Vienna in 2010.



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