



Goal-based Multi-agent Collaboration Community Formation: A Conceptual Model

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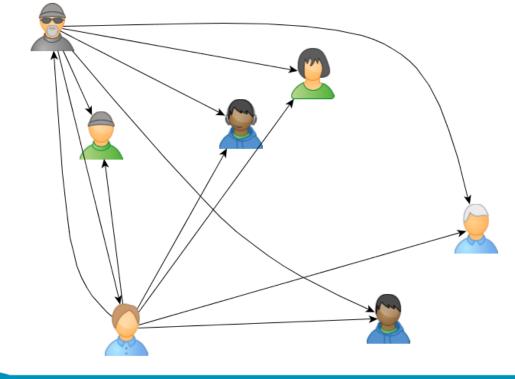
Outline

- > What is the problem?
- Solution Design: A Conceptual Model
- Results

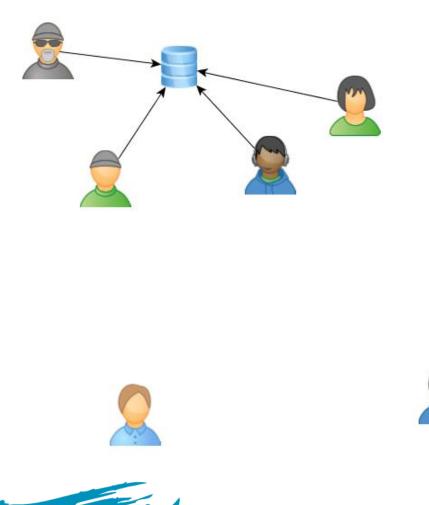


What is the problem?

- A Network of agents
- Their aim is to form a collaboration community to achieve a shared goal
- No predefined network structure or completely connected network structure
- Large number of links between agents (Large number of possible combination)
- Computational Complexity
- Not flexible enough for dynamic open systems

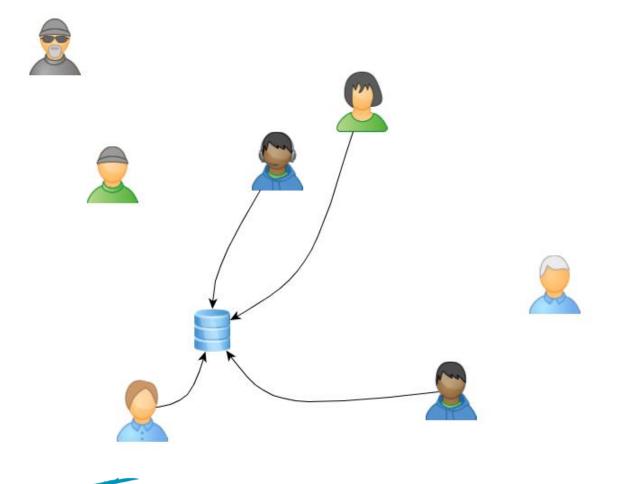


Solution: Defining Neighborhoods



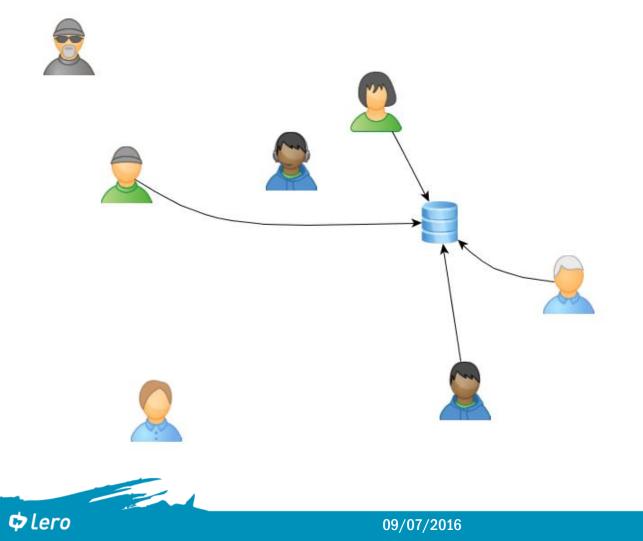


Solution: Defining Neighborhoods

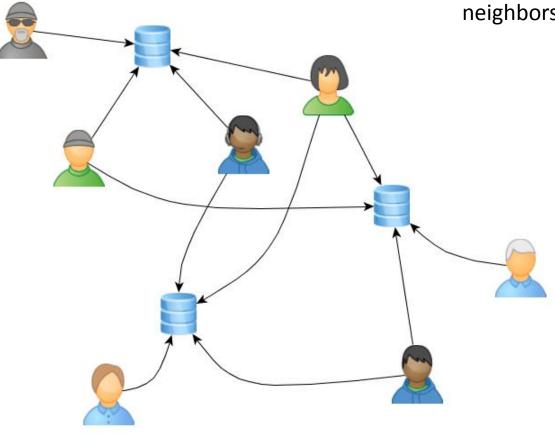


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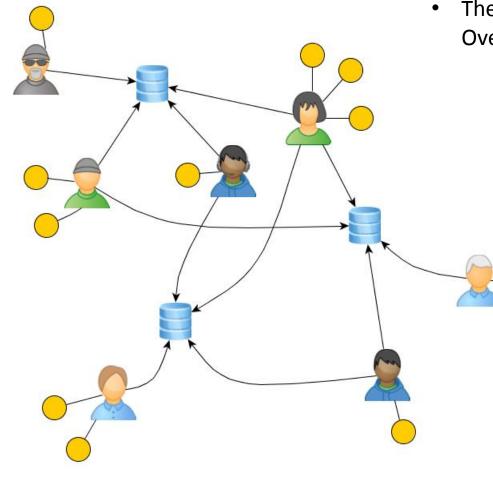
Solution: Defining Neighborhoods



- Defining Neighborhoods
- Agents are able to communicate with their neighbors



What is the problem, Now?

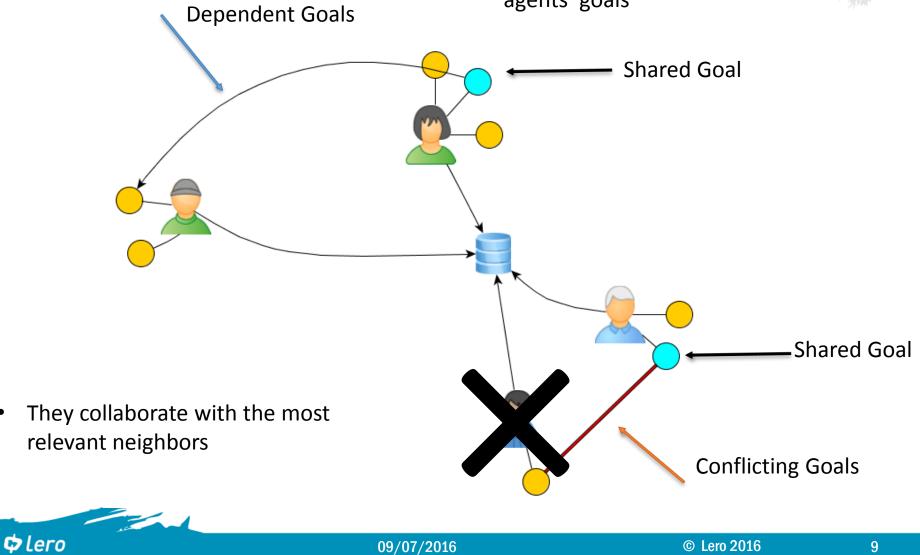


- Agents have different individual and shared goals and policies
- They might have Conflicting Goals, Overlapping Goals,
 - Who are the collaborators?
 - How to nominate agents with no conflicting goals or interest ?
 - How to balance shared goal and individual goal achievement?

Our Solution

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- Agents' Goal Relation Type Model
- Different dependencies between agents' goals

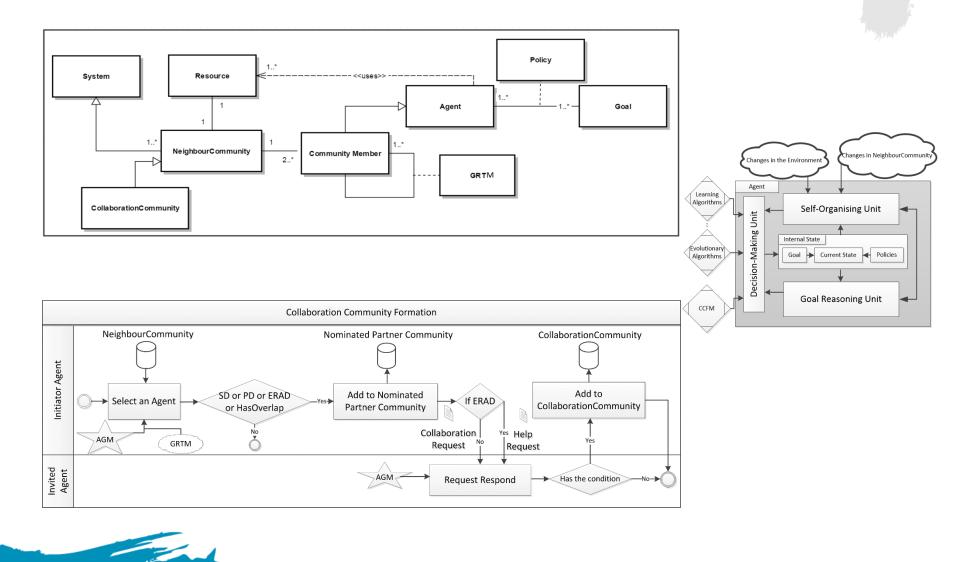


Our Solution

- Lower Computation complexity
- Lower number of links between the agents
- No interest conflict between the collaborating agents
- Applicable for dynamic and open multiagent systems



Solution Design: A Conceptual Model

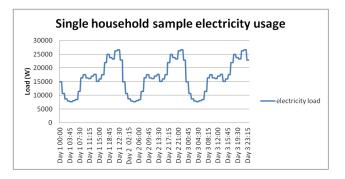


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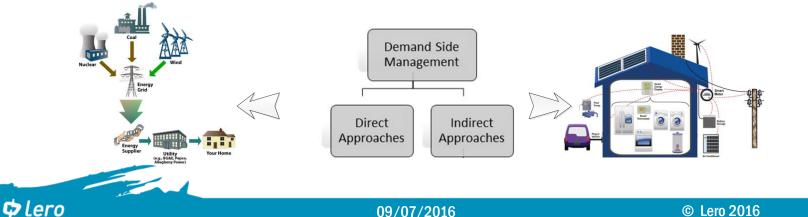
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Demand Side Management

- Demand side management (DSM): modification of ≻ the consumers' electricity consumption with respect to their expected consumption.
 - Main goal: make the most of current energy capacity and avoiding ≻ new higher peaks
 - > range of approaches: energy efficiency, fuel substitution, demandresponse and residential/ commercial load management
 - Residential Demand side management : Energy usage not ≻ distributed evenly during the day: morning peak, large evening peak, valley during the night.
 - > peak clipping, valley filling, load shifting



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Smart-Grid Scenario

> 80 Electrical Vehicles(EV),10 Emergency Electrical Vehicle(EEV)

- A Daily Plan (departure/arrival time, Distance to work)
- Individual Goal (have enough charge to complete next journey)
- Shared Goal (decreasing the transformer overload and utilize the offpeak available capacity of the grid)
- Each agent has its own control thread and decide the next action for the next time step
- They collaborate if their decided actions result in transformer overload.



Evaluation

Experimental Setup

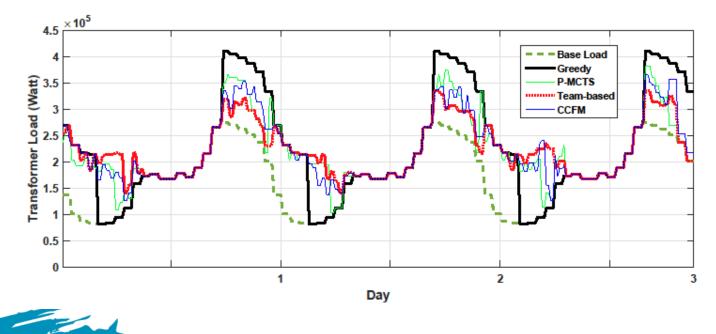
	Number of Agents	Arrival/Departu re time	Distance to work Miles (KM)	Implemented methods	Base Load
Scenario III	90	Between 6am- 6pm	45 (~72 KM)	Greedy-PMCTS- MAMCTS-CPMCTS	Yes

- Performance Criteria
 - Peak To Average Ratio = $\frac{Max \ Load}{Average \ Load}$
 - Transformer Load
 - SoC (EV's State of Charge)



Results

		Statistical Analysis						
		PAR	Transformer Overload	EV SoC ≤ 0	EEV SoC <100	STDEV		
Day 1	P-MCTS	1.66	12	0	0	6.61		
	Team-based	1.45	0	4	3	24.78		
	CCFM	1.59	5	3	0	6.35		
Day 2	P-MCTS	1.78	11	0	0	6.67		
	Team-based	1.51	0	0	4	24.78		
	CCFM	1.55	4	0	0	6.75		
Day 3	P-MCTS	1.76	13	0	0	6.88		
	Team-based	1.49	0	3	4	19.40		
	CCFM	1.63	9	0	0	6.84		



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Many Thanks!

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